

ESTD

Engineering Science &
Technology Division

Mobile Manipulator Motion-Planning with Time-Varying Constraints

In process---will be completed soon.

AND ENERGETIC SYSTEMS
ROBOTICS RESG GROUP

Point of Contact:

Dr. François Pin (865-574-6130, pinfg@ornl.gov)
Oak Ridge National Laboratory, P.O. Box 2008,
Oak Ridge, TN 37831-6305